Default Risk of a Time-homogeneous Diffusion $Model^{[1]}$

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Default Risk of a Diffusion Model

- 1. Introduction
- 2. A main result
- 3. On the auxiliary quantity A(a, b, c)
- 4. On the differentiability of $p(\cdot)$ at b
- 5. Numerical examples

1. Introduction

- 2. A main result
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- The traditional study of default risk usually defines default as the event that the firm value goes below a too low level a. In particular, a = 0 in classical ruin theory.
- In real world, however, the firm is also regarded as defaulted if its value constantly stays below a moderately low level *b* for a certain time period *c*, even though the hitting to level *b* does not immediately lead to illiquidity of the firm.
- Economic justifications for such a consideration are the US bankruptcy codes Chapter 7 (Liquidation) and Chapter 11 (Reorganization).

Default subject to two thresholds and one grace period

- Suppose that the value process is modeled by $X = \{X_t, t \ge 0\}$ with $X_0 = x_0$.
- For a real number x, denote by T_x the first hitting time to level x.
- Let *a* < *b* and *c* > 0 be three exogenously determined constants, with *a* interpreted as the liquidity threshold, *b* as the reorganization threshold and *c* as the grace period.
- Let τ_b(c) be the first time when the process X has constantly stayed below level b for c units of time.
- See the graphs for $\underline{T_a}$ and $\underline{\tau_b(c)}$.
- The default probability is defined by

$$q(x_0) = q(x_0; a, b, c) = \mathbb{P}^{x_0} \{ T_a \wedge \tau_b(c) < \infty \}.$$
 (1.1)

• It is sometimes more convenient to start with the non-default probability $p(x_0) = 1 - q(x_0)$.

Some immediate remarks

Letting $a \downarrow -\infty$ and b = 0 in (1.1) yields

$$q(x_{0};-\infty,0,c)=\mathrm{P}^{x_{0}}\left\{ au_{0}(c)<\infty
ight\}$$
 ,

which is recognized as Parisian ruin probability.

Clearly, $q(x_0; a, b, c)$ is decreasing in c. Letting $c \downarrow 0$ in (1.1) yields

$$q(x_{0};$$
 a, $b,$ $+0)=\mathrm{P}^{x_{0}}\left\{ \, {T}_{b}<\infty
ight\}$,

while letting $c \uparrow \infty$ yields

$$q(x_0; extbf{a}, extbf{b}, \infty) = \mathrm{P}^{x_0} \left\{ extbf{T}_{ extbf{a}} < \infty
ight\}.$$

Hence, the grace period c serves as a bridge connecting the two traditional default probabilities:

$$\mathrm{P}^{\mathrm{x}_0}\left\{\mathit{T}_{\mathsf{a}}<\infty
ight\}\leq q(\mathit{x}_0;\mathit{a},\mathit{b},\mathit{c})\leq\mathrm{P}^{\mathit{x}_0}\left\{\mathit{T}_b<\infty
ight\}$$

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Suppose that the firm value is modeled by a time-homogeneous diffusion process $X = \{X_t, t \ge 0\}$, with dynamics

$$dX_t = \mu(X_t)dt + \sigma(X_t)dW_t.$$
(2.1)

In (2.1):

- $X_0 = x_0$ is the initial wealth,
- $\{W_t, t \ge 0\}$ is a standard Brownian motion (Wiener process),
- and $\mu(\cdot)$ and $\sigma(\cdot) > 0$ are two measurable functions satisfying usual conditions of the existence and uniqueness theorem for the stochastic differential equation (2.1).

Denote by $\{\mathcal{F}_t, t \ge 0\}$ the natural filtration generated by $\{W_t, t \ge 0\}$.

The two-sided exit problem

Define

$$G(x) = \exp\left\{-\int^x \frac{2\mu(y)}{\sigma^2(y)} \mathrm{d}y\right\}, \qquad S(x) = \int^x G(y) \mathrm{d}y.$$

The function $S(\cdot)$ is referred to as the scale function of X. To avoid triviality, we assume that $S(\infty) < \infty$.

It is well known that, for u < x < v,

$$P^{x} \{ T_{u} < T_{v} \} = \frac{\int_{x}^{v} G(y) dy}{\int_{u}^{v} G(y) dy}, \qquad P^{x} \{ T_{u} > T_{v} \} = \frac{\int_{u}^{x} G(y) dy}{\int_{u}^{v} G(y) dy}.$$
 (2.2)

Letting $v = \infty$ in second relation in (2.2) yields

$$P^{x}\left\{T_{u}=\infty\right\}=\frac{\int_{u}^{x}G(y)dy}{\int_{u}^{\infty}G(y)dy}.$$
(2.3)

Introduce an auxiliary quantity

$$A(a, b, c) = \lim_{\varepsilon \downarrow 0} \frac{\mathrm{P}^{b-\varepsilon} \{T_b > T_a \wedge c\}}{\varepsilon}.$$
 (2.4)

It will be proved later that A(a, b, c) exists, is finite and equals the boundary derivative of the solution of a PDE. Hence, its value can be easily determined numerically.

Theorem 2.1 For $a < b \le x_0$ and c > 0, the default probability satisfies

$$q(x_0) = \frac{A(a, b, c)}{A(a, b, c) \int_b^\infty G(y) dy + G(b)} \int_{x_0}^\infty G(y) dy.$$
 (2.5)

Proof of Theorem 2.1

For $x \ge b$, by the strong Markov property,

$$p(x) = P^{x} \{ T_{a} = \infty, \tau_{b}(c) = \infty \}$$

= $P^{x} \{ T_{b} = \infty \} + P^{x} \{ T_{a} = \infty, \tau_{b}(c) = \infty, T_{b} < \infty \}$
= $P^{x} \{ T_{b} = \infty \} + E^{x} [P^{x} \{ T_{a} = \infty, \tau_{b}(c) = \infty, T_{b} < \infty | \mathcal{F}_{T_{b}} \}]$
= $P^{x} \{ T_{b} = \infty \} + P^{x} \{ T_{b} < \infty \} p(b).$ (2.6)

It follows that

$$p'_{+}(b) = \lim_{\varepsilon \downarrow 0} \frac{p(b+\varepsilon) - p(b)}{\varepsilon}$$
$$= q(b) \lim_{\varepsilon \downarrow 0} \frac{P^{b+\varepsilon} \{ T_{b} = \infty \}}{\varepsilon}$$
$$= q(b) \frac{G(b)}{\int_{b}^{\infty} G(y) dy}, \qquad (2.7)$$

where in the last step we used (2.3).

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Proof of Theorem 2.1 (Cont.)

Similarly, for $x \in (a, b)$ we have

$$p(x) = \mathbf{P}^x \left\{ T_a = \infty, \tau_b(c) = \infty \right\} = \mathbf{P}^x \left\{ T_b \leq T_a \wedge c \right\} p(b).$$

By Corollary 3.1 below, the limit A(a, b, c) in (2.4) exists and is finite.

It follows that

$$p'_{-}(b) = \lim_{\varepsilon \downarrow 0} \frac{p(b) - p(b - \varepsilon)}{\varepsilon}$$
$$= p(b) \lim_{\varepsilon \downarrow 0} \frac{P^{b - \varepsilon} \{T_b > T_a \land c\}}{\varepsilon}$$
$$= p(b) A(a, b, c).$$
(2.8)

By Theorem 4.1 below, the function $p(\cdot)$ is differentiable at *b*. Thus, the conjunction of (2.7) and (2.8) gives

$$p(b) = \frac{G(b)}{A(a, b, c) \int_b^\infty G(y) \mathrm{d}y + G(b)}.$$
 (2.9)

Substituting (2.9) into (2.6) and using (2.3), we obtain

$$p(x) = \frac{\int_b^x G(y) dy}{\int_b^\infty G(y) dy} + \frac{\int_x^\infty G(y) dy}{\int_b^\infty G(y) dy} \times \frac{G(b)}{A(a, b, c) \int_b^\infty G(y) dy + G(b)}.$$

Thus, relation (2.5) follows from q(x) = 1 - p(x).

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- **3.** On the auxiliary quantity A(a, b, c)
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A PDE

Consider the modified two-sided exit probability function

$$\phi(x,t; \mathsf{a},b) = \mathrm{P}^x \left\{ T_b \leq T_{\mathsf{a}} \wedge t
ight\}, \qquad \mathsf{a} < x < b, t \geq 0.$$

The following theorem establishes a PDE for this function:

Theorem 3.1 Suppose h(x, t) solves

$$h_t(x, t) = \mu(x)h_x(x, t) + \frac{1}{2}\sigma^2(x)h_{xx}(x, t), \qquad a < x < b, t > 0,$$

with the boundary conditions h(b, t) = 1 and h(a, t) = 0 for $t \ge 0$ while h(x, 0) = 0 for a < x < b. Then

$$h(x,t)=\phi(x,t;a,b),$$
 $a\leq x\leq b,t\geq 0.$

Proof of Theorem 3.1

Applying Itö's formula and noticing that $h_s(X_s, t-s) = -h_t(X_s, t-s)$, $dh(X_s, t-s)$ $= -h_t(X_s, t-s)ds + h_x(X_s, t-s)dX_s + \frac{1}{2}h_{xx}(X_s, t-s)\sigma^2(X_s)ds$ $= h_x(X_s, t-s)\sigma(X_s)dW_s$.

For a stopping time τ , we have

$$h(X_{\tau\wedge t}, t-\tau\wedge t) = h(x, t) + \int_0^{\tau\wedge t} h_x(X_s, t-s)\sigma(X_s) dW_s.$$

This implies that $h(x, t) = E^{x} [h(X_{\tau \wedge t}, t - \tau \wedge t)].$

Let
$$\tau = T_a \wedge T_b$$
. By the boundary conditions, we have

$$h(x, t) = \mathbf{E}^x \left[h(X_{\tau, t} - \tau) \mathbf{1}_{\{\tau \le t\}} \right] + \mathbf{E}^x \left[h(X_{t, t}, 0) \mathbf{1}_{\{\tau > t\}} \right]$$

$$= \mathbf{E}^x \left[h(a, t - T_a) \mathbf{1}_{\{T_a = \tau \le t\}} \right] + \mathbf{E}^x \left[h(b, t - T_b) \mathbf{1}_{\{T_b = \tau \le t\}} \right] + \mathbf{0}$$

$$= \mathbf{0} + \mathbf{P}^x \left\{ T_b \le T_a \wedge t \right\} + \mathbf{0}.$$

By the well-known regularity theory of PDE (see, e.g. Theorem 4.22 of Lieberman (1996)), we immediately have the following:

Corollary 3.1 It holds for every fixed t > 0 that $\phi_x(x, t; a, b)|_{x=b}$ is finite and continuous with respect to t. In particular,

$$A(a, b, c) = \lim_{\varepsilon \downarrow 0} \frac{P^{b-\varepsilon} \{T_b > T_a \land c\}}{\varepsilon}$$
$$= \lim_{\varepsilon \downarrow 0} \frac{1 - \phi(b - \varepsilon, c; a, b)}{\varepsilon}$$
$$= \phi_x(x, c; a, b)|_{x=b}$$

exists and is finite.

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Laplace transforms of the two-sided exit times

Suppose that $g_1(\cdot; r)$ and $g_2(\cdot; r)$ are two independent positive solutions of

$$\frac{1}{2}\sigma^{2}(x)g''(x) + \mu(x)g'(x) = rg(x), \qquad r \ge 0,$$

with $g_1(\cdot; r)$ decreasing and $g_2(\cdot; r)$ increasing. Define

$$f(y, z; r) = g_1(y; r)g_2(z; r) - g_1(z; r)g_2(y; r).$$

The Laplace transforms of the two-sided exit times for the diffusion process X were first solved by Darling and Siegert (1953):

Lemma 4.1 For $u \le x \le v$ and $r \ge 0$, we have

$$\mathbf{E}^{x}\left[\mathbf{e}^{-rT_{u}}; T_{u} < T_{v}\right] = \frac{f(x, v; r)}{f(u, v; r)}, \qquad \mathbf{E}^{x}\left[\mathbf{e}^{-rT_{v}}; T_{v} < T_{u}\right] = \frac{f(u, x; r)}{f(u, v; r)}.$$

On the minimum of two exit times

Lemma 4.2 For all x,

$$\lim_{\varepsilon \downarrow 0} \frac{\mathrm{E}^{x} \left[T_{x+\varepsilon} \wedge T_{x-\varepsilon} \right]}{\varepsilon^{2}} = C(x),$$

where C(x) > 0 is a finite constant with an explicit expression.

Proof. By Lemma 4.1,

$$E^{x} [T_{x-\varepsilon}; T_{x-\varepsilon} < T_{x+\varepsilon}] = -\frac{\partial}{\partial r} E^{x} \left[e^{-rT_{x-\varepsilon}}; T_{x-\varepsilon} < T_{x+\varepsilon} \right] \bigg|_{r=0}$$
$$= -\frac{\partial}{\partial r} \frac{f(x, x+\varepsilon; r)}{f(x-\varepsilon, x+\varepsilon; r)} \bigg|_{r=0} = \dots$$

A similar relation for $E^x [T_{x+\epsilon}; T_{x+\epsilon} < T_{x-\epsilon}]$ holds. Therefore,

$$\begin{split} \mathrm{E}^{\mathrm{x}}\left[T_{x+\varepsilon} \wedge T_{x-\varepsilon}\right] &= \mathrm{E}^{\mathrm{x}}\left[T_{x+\varepsilon}; \, T_{x+\varepsilon} < T_{x-\varepsilon}\right] + \mathrm{E}^{\mathrm{x}}\left[T_{x-\varepsilon}; \, T_{x-\varepsilon} < T_{x+\varepsilon}\right] \\ &= \mathsf{Taylor's \ expansion} = \dots \end{split}$$

A lemma

Lemma 4.3 $P^b \{ \tau_b(c) < T_{b-\varepsilon} \} = O(\varepsilon^2)$ as $\varepsilon \downarrow 0$. **Proof.** For X starting with b, denote the consecutive down-crossing and up-crossing times of levels b and $b + \varepsilon$ by

$$0 = \gamma_0^- < \gamma_0^+ < \cdots < \gamma_{i-1}^- < \gamma_{i-1}^+ < \gamma_i^+ < \cdots$$

Then, by the strong Markov property of X and Lemma 4.2,

$$P^{b} \{ \tau_{b}(c) < T_{b-\varepsilon} \} = \sum_{i=0}^{\infty} P^{b} \{ \gamma_{i}^{-} < \tau_{b}(c) < \gamma_{i}^{+} \wedge T_{b-\varepsilon} \}$$

$$= \sum_{i=0}^{\infty} E^{b} \left[E^{b} \left[1_{\{\gamma_{i}^{-} < \tau_{b}(c) < \gamma_{i}^{+} \wedge T_{b-\varepsilon} \}} \middle| \mathcal{F}_{\gamma_{i}^{-}} \right] \right]$$

$$= P^{b} \{ \tau_{b}(c) < T_{b+\varepsilon} \wedge T_{b-\varepsilon} \} \sum_{i=0}^{\infty} P^{b} \{ \gamma_{i}^{-} < T_{b-\varepsilon} \}$$

$$\leq \frac{1}{c} E^{b} \left[T_{b+\varepsilon} \wedge T_{b-\varepsilon} \right] \sum_{i=0}^{\infty} \left(P^{b} \{ T_{b+\varepsilon} < T_{b-\varepsilon} \} \right)^{i}$$

$$= O \left(\varepsilon^{2} \right).$$

Theorem 4.1 The function $p(\cdot)$ is differentiable at *b*.

Proof. By (2.7), it suffices to show that

$$\lim_{\varepsilon \downarrow 0} \frac{p(b) - p(b - \varepsilon)}{\varepsilon} = q(b) \frac{G(b)}{\int_b^\infty G(y) \mathrm{d}y}.$$
 (4.1)

Proof of Theorem 4.1 (Cont.)

For small $\varepsilon > 0$, we split p(b) into two parts as

$$\mathrm{P}^b\left\{\tau_b(c)=\infty,\, T_{b-\varepsilon}=\infty\right\}+\mathrm{P}^b\left\{T_a=\infty,\tau_b(c)=\infty,\, T_{b-\varepsilon}<\infty\right\}.$$

By Lemma 4.3, the first term equals

$$\mathbf{P}^{b}\left\{T_{b-\varepsilon}=\infty\right\}-\mathbf{P}^{b}\left\{\tau_{b}(\boldsymbol{c})<\infty,\ T_{b-\varepsilon}=\infty\right\}=\mathbf{P}^{b}\left\{T_{b-\varepsilon}=\infty\right\}+O(\varepsilon^{2}).$$

With some efforts, we can prove that the second term satisfies

$$\mathbf{P}^{b}\left\{T_{b-\varepsilon}<\infty\right\}p(b-\varepsilon)+o(\varepsilon)$$

It follows that

$$p(b) = \mathbf{P}^{b} \{ T_{b-\varepsilon} = \infty \} + \mathbf{P}^{b} \{ T_{b-\varepsilon} < \infty \} p(b-\varepsilon) + o(\varepsilon),$$

which easily implies (4.1).

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Recall formula (2.5) for the default probability $q(x_0)$:

$$q(x_0) = \frac{A(a, b, c)}{A(a, b, c) \int_b^\infty G(y) dy + G(b)} \int_{x_0}^\infty G(y) dy.$$
(2.5)

The only implicit part is the quantity A(a, b, c).

Theorem 3.1 and Corollary 3.1 enable us to compute A(a, b, c)numerically via a PDE. We use the second-order implicit finite difference method to solve A(a, b, c) for both a Brownian motion and a geometric Brownian motion.

Brownian motion case

Assume $dX_t = \mu dt + \sigma dW_t$, with $x_0 \ge b$, $\mu, \sigma > 0$. Relation (2.5) reduces to (with $\rho = 2\mu/\sigma^2$)

$$q(x_0) = rac{A(a, b, c)}{A(a, b, c) +
ho} \mathrm{e}^{-
ho(x_0 - b)}.$$

Set parameters to $\mu = 0.1$, $\sigma = 0.25$, a = 0.1, b = 0.2 and c = 1. Then

mesh	A(0.1, 0.2, 1)	$q(x_0)$	elapsed time (s)
0.005	8.5534038	$1.3801420 imes e^{-3.2x_0}$	0.505305
0.001	8.4987776	$1.3777311 imes e^{-3.2x_0}$	4.119148
0.0005	8.4919795	$1.3774294 imes e^{-3.2x_0}$	44.813284
0.00025	8.4885830	$1.3772786 imes e^{-3.2x_0}$	342.789096

In the meantime,

$$\begin{split} \mathrm{P}^{x_0} \left\{ \mathcal{T}_a < \infty \right\} &= 1.3771278 \times \mathrm{e}^{-3.2x_0}, \\ \mathrm{P}^{x_0} \left\{ \mathcal{T}_b < \infty \right\} &= 1.8964809 \times \mathrm{e}^{-3.2x_0}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.6932042 \times \mathrm{e}^{-3.2x_0}. \end{split}$$

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Geometric Brownian motion case

Assume $dX_t = \mu X_t dt + \sigma X_t dW_t$, with $x_0 \ge b$ and $\rho = 2\mu/\sigma^2 > 1$. Relation (2.5) reduces to

$$q(x_0) = \frac{A(a, b, c)}{A(a, b, c) + \rho - 1} \left(\frac{b}{x_0}\right)^{\rho - 1}$$

Set parameters to $\mu = 0.1, \ \sigma = 0.25, \ a = 0.1, \ b = 0.2$ and c = 1. Then

mesh	A(0.1, 0.2, 1)	$q(x_0)$	elapsed time (s)
0.005	11.495846	$0.024334255 \times x_0^{-2.2}$	0.460361
0.001	11.145638	$0.024212051 \times x_0^{-2.2}$	4.881175
0.0005	11.101517	$0.024196199 \times x_0^{-2.2}$	37.679470
0.00025	11.079429	$0.024188223 \times x_0^{-2.2}$	287.741042

In the meantime,

$$\begin{split} \mathrm{P}^{x_0} \left\{ T_a < \infty \right\} &= 0.0063095734 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ T_b < \infty \right\} &= 0.028991187 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.014533261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c) < \infty \right\} &= 0.01453261 \times x_0^{-2.2}, \\ \mathrm{P}^{x_0} \left\{ \tau_b(c)$$

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Default Risk of a Diffusion Model

- Consider a more general firm value process of strong Markov property;
- Incorporate (heavy-tailed) jumps into the modeling;
- Consider the more practical finite-time case.

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Thank You Very Much!!!